Product data sheet Characteristics

59737

motor - M87 - Sepam series 80



Main		
Relay application	Motor	
Range of product	Sepam series 80 Sepam series 80 NPP	
Device short name	M87	
Control and monitoring type	Circuit breaker/contactor control ANSI code: 94/69 (option) Latching/acknowledgement ANSI code: 86 Logic discrimination ANSI code: 68 (option) Switching of groups of settings Annunciation ANSI code: 30 Logipam programming (ladder language) (option) Logic equation editor 200 operators Load shedding/automatic restart	
Metering type	Positive sequence voltage Vd/rotation direction Frequency Calculated active and reactive energy (+/- W.h, +/- VAR.h) Active and reactive energy by pulse counting (+/- W.h, +/- VAR.h) (option) Phase current I1, I2, I3 RMS Demand current IM1, IM2, IM3 Peak demand current IM1, IM2, IM3 Measured residual current I'0 Voltage U21, U32, U13, V1, V2, V3 Residual voltage V0 Negative sequence voltage Vi Active power P, P1, P2, P3 Reactive power Q, Q1, Q2, Q3 Apparent power S, S1, S2, S3 Peak demand power PM, QM Power factor Temperature (16 RTDs) (option) Phase current I'1, I'2, I'3 RMS Rotation speed (option) Neutral point voltage Vnt Measured residual current I0, calculated I'0∑ Calculated residual current I'0∑	
Network and machine diagnosis type	Unbalance ratio/negative sequence current li Disturbance recording Thermal capacity used Remaining operating time before overload tripping Waiting time after overload tripping Running hours counter/operating time Starting current and time Start inhibit time, number of starts before inhibition Tripping context	

Phase fault and earth fault trip counters Harmonic distortion (THD), current and voltage Ithd, Uthd Apparent positive sequence impedance Zd Apparent phase-to-phase impedances Z21, Z32, Z13 Differential current Idiff1, idiff2, Idiff3 Through current It1, It2, It3 Current phase displacement θ Phase displacement Datalog (DLG) Motor start report (MSR) Motor start trend (MST) Switchgear diagnosis type Cumulative breaking current CT/VT supervision ANSI code: 60FL Trip circuit supervision ANSI code: 74 (option) Auxiliary power supply monitoring Nb of operations, operating time, charging time, nb of racking out operations (option)

Complementary

Type of measurement	Temperature Power (P,Q) Peak demand power Power factor Voltage Energy Frequency Current Harmonic distorsion (I THD & U THD) Rotation speed	
Protection type	Phase undercurrent ANSI code: 37 Starts per hour ANSI code: 66 Neutral voltage displacement ANSI code: 59N Breaker failure ANSI code: 50BF Directional earth fault ANSI code: 67N/67NC Overvoltage (L-L or L-N) ANSI code: 59 Temperature monitoring (16 RTDs) ANSI code: 38/49T (option) Thermal overload for machines ANSI code: 49RMS Excessive starting time, locked rotor ANSI code: 48/51LR Field loss (underimpedance) ANSI code: 40 Pole slip ANSI code: 78PS Overspeed (2 set points) ANSI code: 12 (option) Underspeed (2 set points) ANSI code: 14 (option) Directional reactive overpower ANSI code: 32Q Machine differential ANSI code: 87M Negative sequence/unbalance ANSI code: 46 Overfrequency ANSI code: 81H Underfrequency ANSI code: 81L Positive sequence undercurrent ANSI code: 27D Remanent undervoltage ANSI code: 27R Undervoltage (L-L or L-N) ANSI code: 27 Negative sequence overvoltage ANSI code: 47 Phase overcurrent ANSI code: 50/51 Earth fault/sensitive earth fault ANSI code: 500/51G Directional active overpower ANSI code: 32P	
Communication port protocol	Measurement readout (option): Modbus Remote indication and time tagging of events (option): Modbus Remote control orders (option): Modbus Remote protection setting (option): Modbus Transfer of disturbance recording data (option): Modbus	
Input output max capacity	42 inputs + 23 outputs	
Communication compatibility	IEC 61850 Modbus RTU Modbus TCPIP DNP3 IEC 61850 goose message IEC 60870-5-103	
User machine interface type	Remote Without Mimic-based Advanced	

Packing Units

Package 1 Weight	0.001 kg	
Package 1 Height	0.010 dm	
Package 1 width	0.010 dm	
Package 1 Length	0.020 dm	